

# Design of two layer clamped-clamped microsensor based on classical and non-classical theories

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## Abstract

In this paper, the two-layer micro sensor is modeled as a two-layer clamped-clamped microbeam and it is optimized by using the genetic algorithm. Using the results of this research, clamped-clamped microbeams can be designed in such a way that the performance of microsensors whose structure includes these microbeams will be improved. The quality factor, the sensitivity, and the maximum stress are selected as objective functions. The sensitivity and the quality factor are the functions of the natural frequency. The natural frequency is calculated based on Rayleigh's method. The quality factor is calculated by approximation established on the one layer's quality factor formula. To calculate the maximum stress, the system is assumed as a mass-spring system that has a harmonic displacement and the maximum deflection is the static deflection. The thickness of each layer, the width of the microbeam, and the length of the microbeam are selected as design variables. The optimization is done based on classical and non-classical theory by the genetic algorithm. The results based on both theories are approximately equal. The length of the microbeam is the most important variable and very changes (approximately 190%). The thickness of the silicon layer has the least effect on the results and changes just lower than  $2\mu m$  (approximately 20%). The results show that when the maximum stress decreases and the sensitivity increases, the quality factor decreases which is undesirable. Maximum sensitivity obtains when the microbeam is very small.

## Keywords:

Microsensor, Clamped-clamped microbeam, Optimization, Sensitivity, Quality factor

## 1. Introduction:

Micro Electromechanical Systems (MEMS) is one of the most important devices used in many fields. In the last two years, microsensors are noticed because of their ability to detect low-mass particles. Narita et.al [1] reviewed piezoelectric and magnetostrictive biosensor materials for the detection of viruses. They reported sensitivity and quality factor are the most important functions that describe the accuracy and

quality of the sensing. Pachkawade et.al reviewed sensors for the detection and measurement of ultra-fine particles. They investigated micro resonant mass sensors including piezoelectric transducers, piezoelectric mass sensors, and thermally actuated resonant transducers. They also reported some parameters such as the size limit of particles and detection range of the microsensors. Lifshitz et.al [2] calculated thermoelastic damping in micro- and nanomechanical systems. They used Zener's standard model of the linear anelastic solid. They derived governing equation of the isothermal micro or nanobeams while there is no thermoelastic coupling but there is the modified thermoelastic strain. They could calculate the quality factor for these models of beams. Dennis et.al [3] modeled and simulated the effect of air damping on the frequency and quality factor of Complementary Metal-Oxide Semiconductor (CMOS) MEMS devices and Pan et.al [4] calculated the quality factor of three-layer Kirchhoff–Love microplate considering three-dimensional heat conduction.

A common model of the MEMS especially microsensors is the microbeam. To calculate different parameters of micro beams, a suitable model is necessary. There are many studies about the modeling of microbeams. Approximately in all of these studies, non-classical theories are used to obtain governing equations. These theories consider the size effect on the strain energy [5-11]. The following is an overview of some of these researches:

Kong et.al [12] calculated the size-dependent natural frequency of Bernoulli- Euler microbeam. The governing equations are obtained based on the modified couple stress theory and by using Hamilton's principle. Park et.al [13] and Gao et.al [14] investigated Bernoulli-Euler and Timoshenko micro beam based on the modified couple stress theory respectively.

Rahi [15] analyzed the vibration of multi-layer micro beams based on the modified couple stress theory. The strain and kinetic energy of multi-layer microcantilever beam were obtained while size effect is considered. The first three frequencies are calculated, and results were validated in the special case that the ratio of material length scale parameter to thickness is zero. Loghman et.al [16] investigated nonlinear vibration of fractional viscoelastic microbeams. They used modified couple stress theory and Bernoulli-Euler beam theory to model the microbeam and derived the equations. Also, they modeled viscoelastic material via the fractional Kelvin–Voigt model. Khabaz et.al [17] analyzed the dynamic and vibration of the sandwich microbeam based on the modified strain gradient theory. They modeled the microbeam as a multi-layer microbeam including a piezoelectric layer. Ding et.al [18] analyzed the size-dependent nonlinear dynamic of microbeams by using the modified couple stress theory. Akgoz et.al [19] analyzed microbeams for various boundary conditions based on the strain gradient theory. Littrel et.al [20] modeled cantilever-based piezoelectric microsensors and micro actuators. Farokhi et.al [21] investigated dynamics of imperfect microbeams, Ansari et.al [22] obtained vibration characteristics of piezoelectric microbeams

based on the modified couple stress theory, Akgoz et.al [23] modeled shear deformation beam, and Talimian et.al [24] investigated dynamic stability of the size-dependent microbeam.

In the recent years, Zhao et.al [25] presented a new Bernoulli–Euler beam model based on modified gradient elasticity, Yin et. al [26] did isogeometric analysis for non-classical Bernoulli-Euler beam model incorporating microstructure and surface energy effects, Esen [27] investigated size-dependent Timoshenko microbeams subjected to a moving load, and Chen [28] et.al reformulated microbeams by incorporating the general strain gradient elasticity theory. Also, some studies modeled microbeams including functionally graded material [29-32].

Kumar et.al [33] analyzed static charge induced pull-in of an electrostatic MEMS. They proposed the non-linear model and derived closed-form expressions of pull-in voltage for different configurations. Sthuti et.al [34] simulated and analyzed suspension based single axis mems capacitive accelerometer. Analytical modeling of the suspensions was presented. Capacitive, displacement and stress analysis of the accelerometer was done. Based on the results, parallel beam suspension is preferred for higher sensitivity and accuracy whereas Folded beam suspension is preferred for greater structural stability. Pakhare et.al [35] investigated effects of shear deformation on the static pull-in Instability behavior of narrow rectangular Timoshenko microbeams. They first calculated results of the maximum beam transverse displacement, for a shear deformable propped-cantilever microbeam under the action of uniformly distributed transverse load, second the finalized six-nodded spectral finite element based on the Timoshenko beam theory was utilized to determine static pull-in instability parameters of narrow microbeams with various fixity conditions and beam thickness to-length ratios. Valizadeh et.al [36] investigated the effects of the material dielectricity on the performance of capacitive micro-devices. They demonstrated the ability of dielectric materials to reduce the required voltage of capacitive MEMS and also to intensify their softening behavior. Vu et.al [37] analyzed functionally graded microbeams with a moving mass based on Timoshenko beam theory. The beam material properties were considered to be graded in the thickness by a power-law function, and they were estimated by Mori-Tanaka scheme. Also, they used modified couple stress theory to captured the size effect. Le et.al [38] used finite element formulation to investigate Size dependent pull-in instability of functionally graded microbeams. Based on Von Kármán nonlinear relationship, a beam element was derived and employed to establish the discretized governing EQ for the microbeams. Results showed that the pull-in voltage was increased by the increase of the power-law exponent and the microscale parameter. One of the best ways for improving the performance of the MEMS is optimization. There are few studies in the literature. Abo-bakr et.al [39] did multi-objective shape optimization of axially functionally graded microbeams. Taati et.al [40] optimized functionally graded material, thickness, and aspect ratio in microbeams embedded in an elastic medium. Fu et.al [41] enlarges the quality factor in microbeams by topology optimization. Gan et.al [42] did a topology optimization design using modified couple stress

theory. Abo-bakr et.al [43] did weight optimization of axially functionally graded microbeams under buckling and vibration behaviors.

As can be seen, microbeams with different models and boundary conditions are used for applications such as making sensors, so their optimal design can improve the performance of devices such as microsensors. The main goal of this research is to find the dimensions of the clamped- clamped microbeam that important functions in the performance of microsensors have their maximum values. It is also worth mentioning that one of the special applications of sensors is to detect the presence of substances such as the corona virus, so the optimal design of such sensors, especially from a mechanical point of view, can increase their efficiency. In this study, multi-objective optimization of two-layer micro clamped- clamped microsensor, which is used to detect viruses, is done by using the genetic algorithm in Matlab. First, the microsensor is modeled as a microbeam that is clamped on both ends. Second, based on the previous studies, sensitivity, quality factor, and stress which are three important parameters of microsensors are selected as objective functions. Also, the dimensions of the microbeam are selected as design variables. In the end, results are shown based on classical and non-classical theories, and the best points are selected.

## 2. Modeling:

Microsensor is modeled as a clamped-clamped microbeam which has 2 layers. One layer is silicon and another one is quartz crystal. Quartz crystal is a piezoelectric material and has a high sensitivity. It is assumed that microbeam is fixed on both ends and don't have any displacement or rotation on the boundary conditions. The modeled is shown in Fig. 1. Thickness of piezoelectric and silicon layer are  $h_1$  and  $h_2$  respectively. Also, length of the microbeam is  $L$  and width of it is  $b$ .

There is no external heat, and the temperature of the environment is  $300 K$ . Viruses are external mass and when they sit on the microbeam, the total mass and the natural frequency of the system are change. The mass of absorbers and electrode layer are very low so in this study they are ignored.

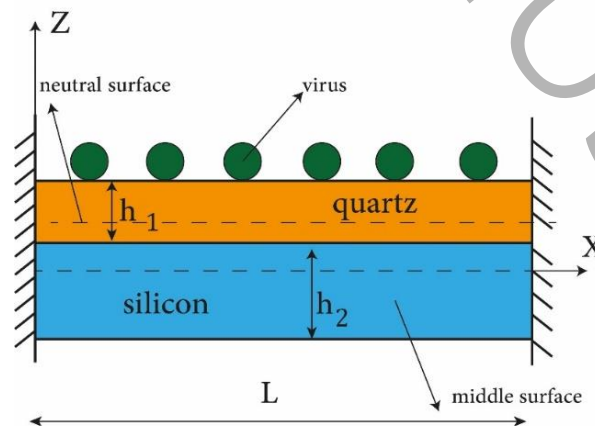


Fig. 1. The model of the microsensor with 2 layer and clamped ends

There are 3 important functions: Sensitivity, Quality factor, and Maximum stress. Sensitivity and quality factor are the important functions of the microsensors [1]. In order to have high measurement quality and accuracy, the values of these functions must be high. On the other hand, for high safety and to prevent failure, maximum stress on the system must be low.

### 2.1. Sensitivity:

The sensitivity is calculated as [1]:

$$S = \frac{\Delta f}{\Delta m} = -\frac{2f_0^2}{A\sqrt{\rho\mu}} \quad (1)$$

Where  $m$  is the mass,  $\rho, \mu$  are the density and the shear modulus of the piezoelectric.  $A$  is the active surface of the piezoelectric layer. In this study all the surface of the quartz is assumed active. Also  $f_0$  is:

$$f_0 = \frac{\omega_0}{2\pi} \quad (2)$$

where  $\omega_0$  is the first circular natural frequency of the system. To calculate  $\omega_0$  Rayleigh's method is used.

Based on Rahi's investigation [15] strain and kinetic energy of the 2 layers microbeam are calculated as:

$$\pi_s = \frac{1}{2} \left\{ \sum_{i=1}^{n=2} E_i \tilde{I}_i + \frac{6E_i \bar{I}_i}{(1+\nu_i)} \left( \frac{l_i}{h_i} \right)^2 \right\} \int_0^L \left[ \left( \frac{\partial^2 w}{\partial x^2} \right)^2 \right] dx \quad (3)$$

$$K = \frac{1}{2} \int_0^L \left[ \left( \sum_{i=1}^{n=2} \rho_i A_i \right) \dot{w}^2 + \left( \sum_{i=1}^{n=2} \rho_i \tilde{I}_i \right) \left( \frac{\partial \dot{w}}{\partial x} \right)^2 \right] dx \quad (4)$$

where  $w$  is the displacement.  $E_i, \rho_i, A_i, h_i$  and  $l_i$  are the Young's modulus, density, area, thickness and material length scale parameter of each layer respectively. Also,  $\nu_i$  is the Poisson's ratio of each layer and  $\bar{I}_i$  is the moment of inertia of each layer about its neutral surface and calculated as:

$$\bar{I}_i = \frac{b_i h_i^3}{12} \quad (5)$$

where  $b_i$  is the width of each layer.

Also  $\tilde{I}_i$  is calculated as:

$$\tilde{I}_i = \bar{I}_i + A_i \bar{z}_{ni}^2 \quad (6)$$

where  $\bar{z}_{ni}$  is the distance between the neutral surface of each layer and the neutral surface of all the system and are calculated as:

$$\begin{aligned}\bar{z}_{n1} &= \frac{1}{2}(h - 2e - h_1) \\ \bar{z}_{n2} &= \frac{1}{2}(h - 2e - h_2) - h_1\end{aligned}\quad (7)$$

where  $h$  is the total thickness of the microbeam and  $e$  is the distance of the neutral surface of all the system from the coordinate system and calculate as:

$$e = \frac{1}{2} \frac{(E_2 - E_1)(h_2^2 - hh_2)}{E_1h - (E_2 - E_1)h_2} \quad (8)$$

It is assumed that the system has a harmonic vibration so  $w$  is defined as:

$$w(x, t) = X(x)T(t) \quad (9)$$

where

$$T(t) = e^{i\omega_0 t} \quad (10)$$

Because the microbeam is fixed on both ends, this function is proposed to satisfy the geometrical boundary conditions:

$$X = X_{max} \left( 1 - \cos\left(\frac{2\pi x}{L}\right) \right) \quad (11)$$

By substituting Eq. (5-10) into Eq. (3-4), the first circular natural frequency is obtained:

$$\omega_0 = \left( \frac{N \left( \frac{8\pi^4}{L^3} \right)}{M(1.5)L + G \left( \frac{2\pi^2}{L} \right)} \right)^{\frac{1}{2}} \quad (12)$$

where

$$\begin{aligned}N &= \left\{ \sum_{i=1}^{n-2} E_i \tilde{I}_i + \frac{6E_i \bar{I}_i}{(1+\nu_i)} \left( \frac{l_i}{h_i} \right)^2 \right\} \\ M &= \left( \sum_{i=1}^{n-2} \rho_i A_i \right)\end{aligned}\quad (13)$$

$$G = \left( \sum_{i=1}^{n=2} \rho_i \tilde{I}_i \right)$$

It should be noted that the above equations are obtained based on the modified Couple stress theory. In this theory, the amount of strain energy is obtained differently than in the classical theory. The amount of strain energy in this theory is obtained from the following relationship:

$$\pi_s = \frac{1}{2} \int_V (\sigma_{ij} \varepsilon_{ij} + m_{ij} \chi_{ij}^s) dV \quad ; \quad i = x, y, z \quad \text{and} \quad j = x, y, z \quad (14)$$

where  $V$  is the volume of the system. In addition, the components of the stress tensor  $\sigma_{ij}$ , the strain tensor  $\varepsilon_{ij}$ , the deviatoric part of the symmetric couple stress tensor  $m_{ij}$  and the symmetric curvature tensor  $\chi_{ij}^s$  calculated as follows:

$$\sigma_{ij} = 2\mu\varepsilon_{ij} + \lambda\varepsilon_{kk}\delta_{ij} \quad ; \quad m_{ij} = 2\mu l^2 \chi_{ij}^s \quad (15)$$

$$\varepsilon_{ij} = \frac{1}{2}(u_{i,j} + u_{j,i}) \quad ; \quad \chi_{ij}^s = \frac{1}{2}(\theta_{i,j} + \theta_{j,i}) \quad (16)$$

$$\theta_i = \frac{1}{2} \varepsilon_{ijk} u_{k,j} \quad (17)$$

where,  $\theta_{i,j}$  is the gradient of rotation,  $\theta_i$  is infinitesimal rotation vector,  $\varepsilon_{ijk}$  is alternating tensor (or permutation symbol), and  $u_i$  is components of the displacement vector. The parameters  $(\lambda, \mu)$  and  $l$  are called Lamé constants and the material length scale parameter, respectively. The Lamé constants can also be written regarding Young's modulus  $E$  and Poisson's ratio  $\mathcal{G}$  as follows:

$$\lambda = \frac{\mathcal{G}E}{(1+\mathcal{G})(1-2\mathcal{G})} \quad ; \quad \mu = \frac{E}{2(1+\mathcal{G})} \quad (18)$$

The verification of this method is presented in Table 1. Results based on classical theory, non-classical theory, and COMSOL model are compared for single layer and two-layers micro beam. Also, the difference between COMSOL results and the other results are calculated.

Table 1. Results verification based

Number of layers

First natural frequency

	Classical theory	Non-classical theory (Modified couple stress theory)	COMSOL model	Difference COMSOL result with classical result	Difference COMSOL result with non-classical result
<b>Single layer</b>	2.150e5	2.240e5	2.157e5	0.32%	3.84%
<b>Two-layers</b>	5.34e5	5.52e5	5.39e5	0.74%	2.41%

## 2.2. Quality factor:

The quality factor of one-layer microbeam is calculated as [2]:

$$Q^{-1} = \frac{E\alpha^2 T_o}{C_p} \left( \frac{6}{\xi^2} - \frac{6}{\xi^3} \frac{\sinh(\xi) + \sin(\xi)}{\cosh(\xi) + \cos(\xi)} \right) \quad (19)$$

where  $E$  is the Young's modulus,  $C_p$  is the heat capacity,  $\alpha$  is the thermal expansion coefficient,  $T_o$  is the surrounding temperature, and

$$\xi = b \sqrt{\frac{\omega_0}{2\chi}} \quad (20)$$

where

$$\chi = \frac{H}{\rho C_p} \quad (21)$$

where  $H$  is heat conductivity and  $\rho$  is density.

In this study the microbeam is modeled as 2-layer microbeam so above values are substituted by approximated values which are the average of properties values of all layers. These values are defined as:

$$E_e = \frac{E_1 h_1 + E_2 h_2}{h_1 + h_2} \quad (22)$$

$$C_e = \frac{\sum_{i=1}^{n=2} \rho_i h_i C_i}{\sum_{i=1}^{n=2} \rho_i h_i} \quad (23)$$

$$\alpha_e = \frac{\sum_{i=1}^{n=2} \alpha_i h_i}{\sum_{i=1}^{n=2} h_i} \quad (24)$$

$$H_e = \sum_{i=1}^{n=2} \frac{H_i}{h_i} \left( \sum_{i=1}^n h_i \right) \quad (25)$$



$$\rho_e = \frac{\sum_{i=1}^{n=2} \rho_i h_i}{\sum_{i=1}^{n=2} h_i} \quad (26)$$

### 2.3. Maximum stress:

Maximum stress is calculated as [40]:

$$\sigma_{max} = (Ez)_{max} \left( \frac{\partial^2 w}{\partial x^2} \right)_{max} \quad (27)$$

where

$$(Ez)_{max} = (E_i h_i)_{max} \quad (28)$$

According to the Eq. (8-10) for calculation of the maximum values of  $\frac{\partial^2 w}{\partial x^2}$  it is necessary that maximum value of the  $X$  calculate. It is assumed that system is the simple mass-spring system then maximum value of the displacement is defined as:

$$w_{max} = \frac{F}{k} \quad (29)$$

Based on Eq. (11)  $k$  is calculated as:

$$k = N \left( \frac{8\pi^4}{L^3} \right) \quad (30)$$

and  $F$  is the weight of the viruses which is calculated as:

$$F = (\Delta m g) \quad (31)$$

where

$$\Delta m = \left( \frac{A_B}{A_p} \right) m_p = \left( \frac{bL}{A_p} \right) m_p \quad (32)$$

where  $A_B$  and  $A_p$  are the area of microbeam and particles respectively. As a result, maximum stress is calculated as:

$$\sigma_{max} = C \sigma^* \quad (33)$$

where

$$C = \frac{g\rho_p}{A_p} \quad (34)$$

$$\sigma^* = (E_i h_i)_{max} \frac{(bL)}{N \left( \frac{8\pi^4}{L^3} \right)} \left( \frac{2\pi}{L} \right)^2 \quad (35)$$

### 3. Optimization:

Objective functions:

Three important functions of the microsensor are calculated. In the next step the optimization of the microsensor is done by choosing these functions as objective functions. Objective functions are defined as:

$$S = f_1(h_1, h_2, b, L) \quad (36)$$

$$-Q = f_2(h_1, h_2, b, L) \quad (37)$$

$$\sigma^* = f_3(h_1, h_2, b, L) \quad (38)$$

The genetic algorithm is selected for optimization. This algorithm obtains the minimum values of functions so the negative sign should be applied to the quality factor because the maximum value of the quality factor is the target of the design. Also, in Eq. (28),  $C$  is a constant value, so  $\sigma^*$  is selected as an objective function.

Design variables:

Dimensions of the microbeam are selected as design variables:

$$[x_1, x_2, x_3, x_4]^T = [h_1, h_2, b, L]^T \quad (39)$$

There are some limits to make a microbeam, also equations of the microbeam are calculated based on the Euler-Bernoulli beam theory. Some constraints are set to satisfy these conditions:

$$h_1 + h_2 \leq 0.1L \quad (40)$$

$$2(h_1 + h_2) \leq b \quad (41)$$

$$L \geq 3b \quad (42)$$

There are lower and upper bounds for design variables that are shown in Table 1. These bounds are arbitrary.

**Table 2.** Bounds of design variables

Variable	Lower bound( $10^{-6}$ )	Upper bound( $10^{-6}$ )
$x(1)$	10	100
$x(2)$	10	100
$x(3)$	40	300
$x(4)$	200	1000

The optimization is done by Matlab software and numerical results are shown in the next section.

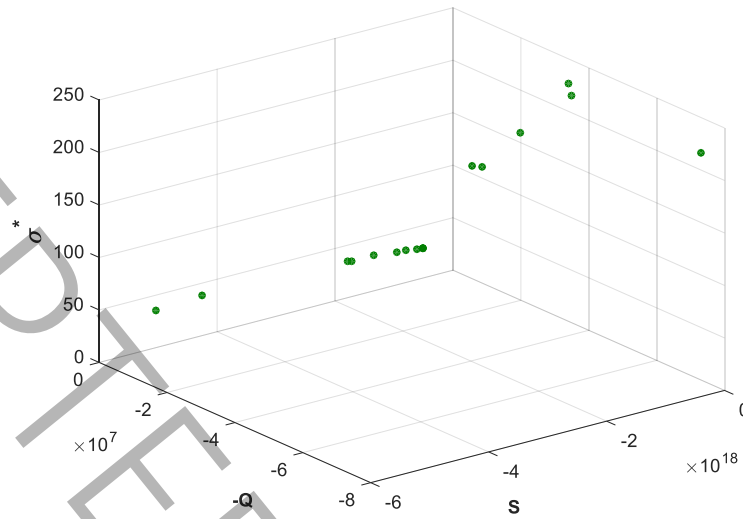
#### 4. The results and discussion

Results of the optimization are presented in this section. Geometrical characteristics were defined in the previous sections. The Mechanical and thermal properties of layers are described in Table 2. Results are obtained based on classical and non-classical theories. To obtain results based on classical theory, ratio of material length scale parameters of each layer ( $l_i$ ) to thickness in Eq. (3) are assumed zero. The best values of functions are shown in Figs. 2 and 3 based on classical and non-classical theories.

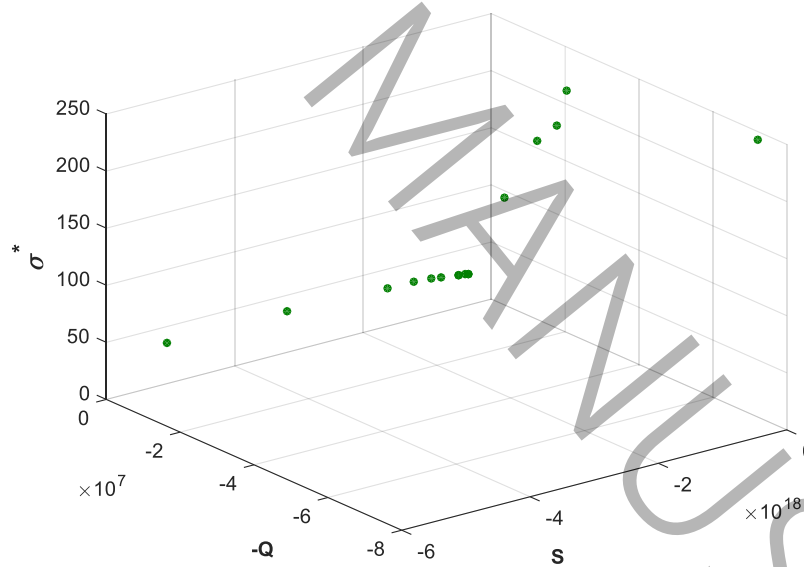
**Table 3.** Properties of each layer [1, 15, 44-46]

Property/material	Unit	SiO <sub>2</sub> (quartz)	Si
E	Gpa	72.52	170
$\nu$	-	0.166	0.22
$\mu$	Gpa	30.97	69.67
$\rho$	kg/m <sup>3</sup>	2650	2233
$l$	Mm	2.4	1
C	J/kg K	700	812.33
H	W/m K	1.3	156
$\alpha$	$10^{-6}/K$	12.3	0.262

Values are approximately equal in both Figs. In other words, the size effect doesn't have a significant effect on the optimization results. It is necessary to mention that the material length scale parameters are assumed constant and if they change according to different sizes, results maybe change. The targets of the design are that the sensitivity and quality factor increase while maximum stress decreases. Results show that when the maximum stress decreases and sensitivity increases, the quality factor decreases which is undesirable. Optimum values are described in Tables 3 and 4 based on classical and non-classical theories. According to Eq. (13), there are some fractions that maybe are very high in special points so in some cases quality factor is inf which is due to the software approximation.



**Fig. 2.** The best values based on the non-classical theory



**Fig. 3.** The best values based on the non-classical theory

When the sensitivity is very high, dimensions are very small and approximately are equal to the lower bounds of design variables. Based on these results, to obtain high quality factor, dimensions, especially length, must increase. In the cases where maximum stress is small, length of the microbeam is between cases that have a high-quality factor or high sensitivity, but the thickness of piezoelectric layer is bigger than others.

Among the design variables, the thickness of the silicon layer has the least changes. It is lower than  $2\mu\text{m}$  (approximately 20%). In other words, this variable has the least effect on the results.

The thickness of the piezoelectric layer changes about  $14\mu\text{m}$  (approximately 140%). When the sensitivity is high, the piezoelectric's thickness is small and when the maximum stress is low, this variable is bigger. About the quality factors, this value in the best cases is between the two previous cases.

The width of the microbeam changes about  $30\mu\text{m}$  (approximately 75%). Same as the thickness of the piezoelectric layer, when the sensitivity is high, the width is small. On the other hand, in the cases that have low maximum stress, the width is big. Also, when the quality factor is very high, the thickness is between two above cases.

The length of the microbeam is the variables which have the most changes and have the most significant effect on the results. These variables change more than  $580\mu\text{m}$  (approximately 190%) in the classical results. As other variables, in the cases that have high sensitivity, the length is the smallest. As the length increasing, the quality factor increases and the sensitivity decreases. This parameter in the low maximum stress cases is between the above cases.

To define the best answers, two methods are used. By using Eq. (38) results are normalized. For each function, points that have the biggest size are converted to 1, and points that have the smallest size are converted to 0:

**Table 3.** Optimum values of design variables and objective functions based on non-classical theory

Design variables				Objective functions		
$h_1 (\mu\text{m})$	$h_2 (\mu\text{m})$	$b (\mu\text{m})$	$L (\mu\text{m})$	$s$	$-Q$	$\sigma^*$
10.00001	10	40.00019	200.0001	-5.37E+18	-5736279	48.48958
10.00001	10.00001	40.00007	207.7847	-4.61E+18	-6110387	52.33772
10.51563	11.1831	43.4092	516.059	-1.26E+17	-inf	282.1554
20.26477	10.03297	63.5008	304.1106	-6.93E+17	-1454709	32.51608
21.5693	10.00099	66.30716	315.7112	-5.81E+17	-1278532	30.90272
14.5928	10.00679	50.44574	246.6532	-1.87E+18	-2696743	39.81831
18.76926	10.08681	59.59902	288.857	-8.92E+17	-1720985	34.11644
10.13651	11.31398	43.23319	349.2757	-6.13E+17	-1.9E+07	135.0965
10.63673	11.74268	45.98299	470.0119	-1.82E+17	-7.6E+07	223.6882
12.24859	11.62389	48.90662	383.5296	-3.78E+17	-1.2E+07	122.0372
10.27186	11.57975	44.37774	402.2959	-3.48E+17	-2.6E+07	173.4422
10.09163	10.88153	45.09498	453.4306	-1.98E+17	-3.7E+07	234.6003

21.36367	10.11554	66.1933	316.4521	-5.79E+17	-1319306	31.66704
15.4833	10.06335	52.56166	259.2738	-1.49E+18	-2502233	39.50558
14.21698	10.04606	49.18312	245.2049	-1.96E+18	-3010588	41.17259
17.71979	10.07649	56.95586	278.8345	-1.06E+18	-1930309	35.52213
21.40262	10.15852	66.48856	315.8192	-5.83E+17	-1306174	31.42743
10.66798	11.73194	46.00252	470.0119	-1.82E+17	-3.8E+07	222.9055

**Table 4.** Optimum values of design variables and objective functions based on classical theory

Design variables				Objective functions		
$h_1 (\mu m)$	$h_2 (\mu m)$	$b (\mu m)$	$L (\mu m)$	S	-Q	$\sigma^*$
10.00001	10.00001	40.00005	200.0002	-5.37E+18	-5511330	48.48959
13.61824	10.84357	49.62435	580.2286	-6.65E+16	-inf	242.7347
21.34046	10.34957	64.84655	316.9401	-5.97E+17	-1406962	31.84542
23.64476	10.41862	69.87262	340.6774	-4.31E+17	-1177935	29.87044
10.21659	11.45183	46.25083	555.908	-9.06E+16	-inf	335.9873
12.57673	10.60218	46.8494	470.574	-1.59E+17	-2.1E+07	183.401
22.67131	10.39453	68.02371	331.058	-4.88E+17	-1263060	30.74419
17.61935	10.34868	56.1217	281.1208	-1.06E+18	-2077547	36.40081
14.88545	10.15388	50.73379	250.3984	-1.78E+18	-2688111	39.48439
11.8323	10.05772	44.0286	218.9021	-3.41E+18	-4076588	44.6944
23.64328	10.41944	69.87345	340.6755	-4.31E+17	-1182053	29.8741
18.80375	10.27264	59.27222	290.7652	-8.86E+17	-1775854	34.4085
16.34789	10.25363	53.60937	266.7668	-1.34E+18	-2325974	37.74193
10.51382	10.97162	45.58434	397.5345	-3.34E+17	-1.8E+07	169.3175
13.18169	10.64089	47.96458	376.6941	-3.79E+17	-9993067	108.687
10.12545	10.58645	44.44293	437.4834	-2.25E+17	-2.4E+07	220.8515
21.33851	10.35104	64.84655	316.9401	-5.97E+17	-1407112	31.85131
10.53269	11.38965	46.58349	487.8446	-1.50E+17	-7.5E+07	248.8711

If points that have the minimum total size are considered the best answers, Eq. (37) must use:

$$\Gamma = \text{Min} \left( -\bar{S} - \bar{Q} + \bar{\sigma}^* \right) \quad (43)$$

And if points that are approximately middle are considered the best answers, Eq. (38) must use:

$$Y = \text{Max}(-\bar{S} - \bar{Q} + \bar{\sigma}^*) \quad (44)$$

Based on Eq. (39-40), the best answers are shown in Table 5.

**Table5.** The best answers

Selection function	Theory	$h_1$ ( $\mu m$ )	$h_2$ ( $\mu m$ )	$b$ ( $\mu m$ )	$L$ ( $\mu m$ )	S	-Q	$\sigma^*$	$\Sigma \bar{\Psi}$
$\Gamma$	Non-classic	10.00	10.00	40.00	200.00	-5.37E+18	-5736279	48.48958	-0.973
	classic	10.00	10.00	40.00	200.00	-5.37E+18	-5511330	48.48959	-0.973
$Y$	Non-classic	10.09	10.88	45.09	453.43	-1.98E+17	-3.7E+07	234.6003	0.515
	classic	10.12	10.58	44.44	437.48	-2.25E+17	-2.4E+07	220.8515	0.544

It is obvious that by using  $\Gamma$  the best answers are obtained at the beginning of the results' interval. When  $Y$  are used, lengths and widths have more changes than the thickness of layers. Also, based on classic theory, thickness of the piezoelectric is bigger, but other variables are smaller.

### 5. Conclusion

In this study the optimization of the clamped-clamped microsensor was done by using genetic algorithm. All of the three objective functions are the important functions that describe accuracy and safety of the system. Sensitivity was the relation between the changes of the mass and changes of the vibration frequency. The quality factor was a function that related to the quality of the measurement and maximum stress was the function that related to the maximum deflection and must be low to increase safety of the system. The microsensor was modeled as a two-layer microbeam which was fixed on both ends. One layer was silicon as a sublayer and another one was quartz as a piezoelectric layer. Rayleigh's method was used to calculate the natural frequency and it was used to calculate the sensitivity and the quality factor. To calculate the maximum stress, the system was assumed as a mass-spring system and the maximum deflection was assumed equal to the static deflection.

Four geometrical dimensions, the thickness of each layer, the width of the beam, and the length of the beam, were selected as design variables. There were some constraints and bounds for these variables. The aims of this optimization were increasing the sensitivity and quality factor also decreasing the maximum stress. The optimization was done by Matlab software and has these results:

- When the maximum stress decreases and the sensitivity increases, the quality factor decreases.
- The maximum sensitivity obtains when dimensions are small.
- Enlarging the sensor increase the quality factor.
- To decrease the maximum stress, the thickness of the piezoelectric must increase.
- The length of the microbeam has the most impact on the functions and has the most changes among the design variables (approximately 190%).
- The least effects were for the thickness of the silicon layer and has the least changes among the design variables (approximately 20%).
- Based on the  $\Gamma$  function, the best answers are at the beginning of the results' interval.
- Compared to results that are obtained based on the  $\Gamma$ , the best points based on the  $Y$  have the bigger dimensions.

As mentioned above, the purpose of this research was to find the dimensions of the microbeam so that all three objective functions can have their best values as much as possible. According to the obtained results, reaching this goal causes the objective functions to be far from their maximum value, but all three functions are close to the initial demand. Considering that the main focus of the problem is to reach all three objective functions to their maximum values simultaneously, the optimal dimensions are obtained according to Eq. (40) and Table 5.

In the future, by considering new functions or applying piezoelectric effects in the equations, new optimal points can be found for the design of a two-layer or multi-layer microbeam.

## 6. Nomenclature

$m$	mass, kg
$E$	Young's modulus, GPa
$A$	Area, m <sup>2</sup>
$h$	thickness, m
$b$	width, m
$\bar{z}$	distance between the neutral surface of each layer and the neutral surface of all the system, m
$e$	is the distance of the neutral surface of all the system from the coordinate system
$l$	material length scale parameter, $\mu\text{m}$
$H$	thermal conductivity, W/m K



C heat capacity, J/kg K

**Greek symbols**

$\rho$  density, kg/m<sup>3</sup>

$\mu$  shear modulus, GPa

$\omega$  natural frequency, radian/second

$\nu$  Poisson's ratio

$\alpha$  the thermal expansion coefficient,  $10^{-6}/K$

$\sigma_{ij}$  stress tensor

$m_{ij}$  symmetric couple stress tensor

$\varepsilon_{ij}$  strain tensor

$\chi_{ij}^s$  symmetric curvature tensor

$\theta_i$  infinitesimal rotation vector

$\theta_{i,j}$  gradient of rotation

$\epsilon_{ijk}$  alternating tensor

$u_i$  components of the displacement vector

$(\lambda, \mu)$  Lamé constants

**Subscript**

$i$  number of layers

**7. References**

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